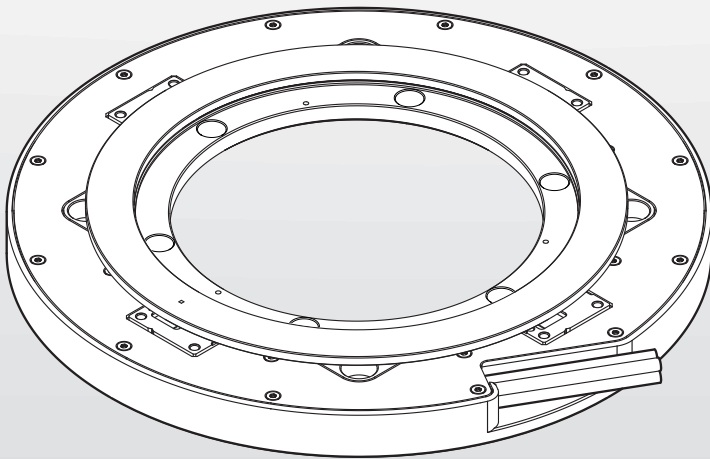




HEIDENHAIN



ERP 1080 Dplus
Commissioning Instructions

Contents

1	Basic information.....	3
1.1	Validity of the documentation.....	3
1.2	Target groups for the instructions.....	3
1.3	Notes on reading the documentation.....	4
1.4	Notes in this documentation.....	5
1.5	Mounting the product.....	5
2	Adjustment and diagnosis.....	6
2.1	Connecting an encoder using its ID.....	7
2.2	Using the mounting wizard.....	9
3	Installation.....	12
3.1	General information.....	12
3.2	Definition of the scanning heads.....	13
3.3	Connecting the encoder.....	13
4	Putting into service.....	14
4.1	Overview.....	14
4.2	Notes.....	15
4.3	Finding the reference position.....	15
4.4	Determining the reference offset.....	16
4.5	Calculating the position value.....	17

1 Basic information

This chapter contains information about the product and these Instructions.

1.1 Validity of the documentation

These Commissioning Instructions are valid for encoders of the ERP 1080 Dplus series.

- ▶ Prior to using the documentation, check whether the documentation and encoder model match

The encoder designation is printed on the ID label.

1.2 Target groups for the instructions

These instructions must be read and observed by every person who performs any of the following tasks:

- Commissioning and configuration

1.3 Notes on reading the documentation

WARNING

Fatal accidents, personal injury or property damage caused by non-compliance with the documentation!

Failure to comply with the documentation may result in fatal accidents, personal injury or property damage.

- ▶ Read the documentation carefully from beginning to end
- ▶ Keep the documentation for future reference

The following table lists the various parts of the documentation in their order of reading priority.

Document type	Description
Addendum	An Addendum supplements or supersedes the corresponding contents of the Operating Instructions and, if applicable, of the Mounting Instructions. If an Addendum is included in the shipment, it has the highest reading priority. All other documentation content retains its validity.
Operating Instructions	The Operating Instructions contain all of the information and safety instructions for the proper and intended operation of the device. The Operating Instructions (English language version) are included in delivery and can also be downloaded in other languages from www.heidenhain.com/documentation . The Operating Instructions must be read prior to commissioning the product. The Operating Instructions have the second highest reading priority.
Mounting Instructions	The Mounting Instructions contain all the information and safety precautions needed for the proper mounting and installation of a product. The Mounting Instructions are not included in delivery and must be downloaded from www.heidenhain.com/documentation .
Commissioning Instructions	These Commissioning Instructions provide all the information and safety precautions needed for the proper commissioning of the product.

Have you found any errors or would you like to suggest changes?

We are continuously striving to improve our documentation for you. Please help us by sending your suggestions to the following e-mail address:

userdoc@heidenhain.de

1.4 Notes in this documentation



Safety precautions

Precautionary statements warn of hazards in handling the device and provide information on their prevention. Precautionary statements are classified by hazard severity and divided into the following groups:

⚠ DANGER
Danger indicates hazards for persons. If you do not follow the avoidance instructions, the hazard will result in death or severe injury .
⚠ WARNING
Warning indicates hazards for persons. If you do not follow the avoidance instructions, the hazard could result in death or serious injury .
⚠ CAUTION
Caution indicates hazards for persons. If you do not follow the avoidance instructions, the hazard could result in minor or moderate injury .
NOTICE
Notice indicates danger to material or data. If you do not follow the avoidance instructions, the hazard could result in property damage .


Informational notes

Informational notes ensure reliable and efficient operation of the device. Informational notes are divided into the following groups:

	The information symbol indicates a tip . A tip provides important additional or supplementary information.
	The book symbol indicates a cross reference . A cross reference leads to external documentation, for example: further documentation from HEIDENHAIN or another supplier.

1.5 Mounting the product

Before you put the product into service, all components must be properly mounted.

	Further information can be found in the Mounting Instructions. <ul style="list-style-type: none"> ▶ www.heidenhain.com/documentation ▶ Enter document ID 1409177
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2 Adjustment and diagnosis

This chapter describes how adjustment and diagnosis are performed using the PWM 21 and the Adjusting and Testing Software (ATS).

The PWM 21 testing device together with the ATS software serves for the diagnosis and adjustment of HEIDENHAIN encoders.

It consists of the following components:

- PWM 21
- ATS software, version 3.6.01, with integrated local encoder database for automatic encoder identification

The ATS software is available for download free of charge from the software download area on the HEIDENHAIN website.



For more information, see the associated **Adjusting and Testing Software** documentation.

- ▶ www.heidenhain.com/documentation
- ▶ Enter the document ID **543734**

2.1 Connecting an encoder using its ID

i You need to perform the adjustment and diagnosis for every scanning head.

- ▶ Double-click **Connect the encoder** in the function menu

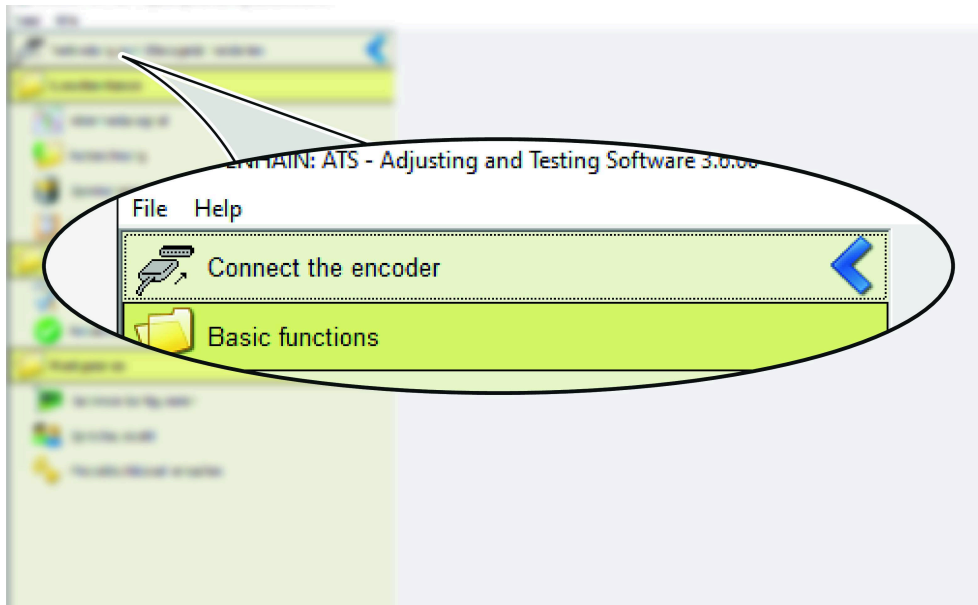


Figure 1: **Function menu**

- ▶ The Adjusting and Testing Software displays the **Encoder selection** dialog.
- ▶ Enter the encoder ID of the connector in the **ID number** field

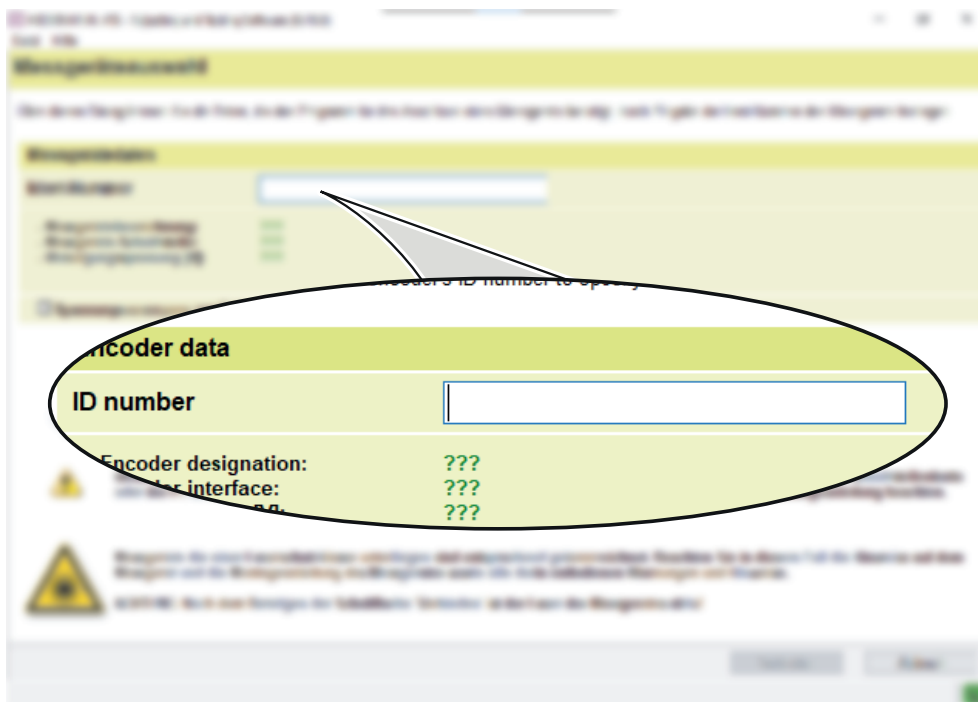


Figure 2: **Encoder selection** dialog

- > The determined encoder parameters are shown in the **Encoder data** field.
- ▶ Click **Connect**
- > The connection to the encoder is established.
- > The **Function menu** is displayed.

2.2 Using the mounting wizard

- ▶ Double-click **Mounting**

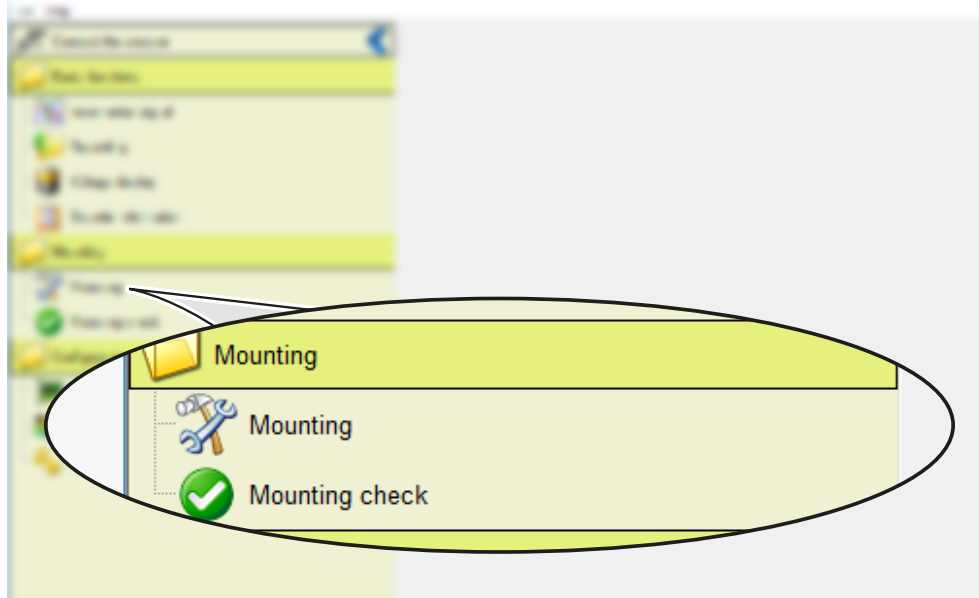


Figure 3: **Function menu**

- ▶ **Confirm message** to continue
- ▶ The **mounting wizard** now opens.
- ▶ Click **Settings** to change the **settings that are currently set**

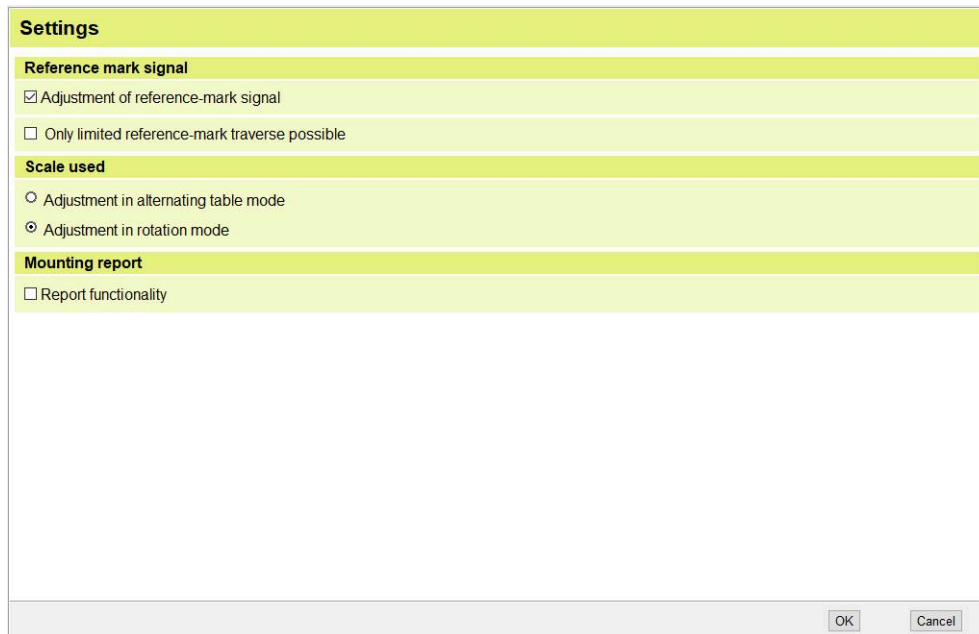


Figure 4: Settings

- ▶ Click **OK**
- ▶ Click **Next**
- > The **Step 1: Mounting the encoder** dialog appears.
- ▶ Click **OK**
- > The **Step 2: Mechanical mounting** dialog appears.
- ▶ Click **Next**
- > The **mounting wizard** dialog with the **Step 3: Adjusting the incremental signals and the reference pulse** message appears.

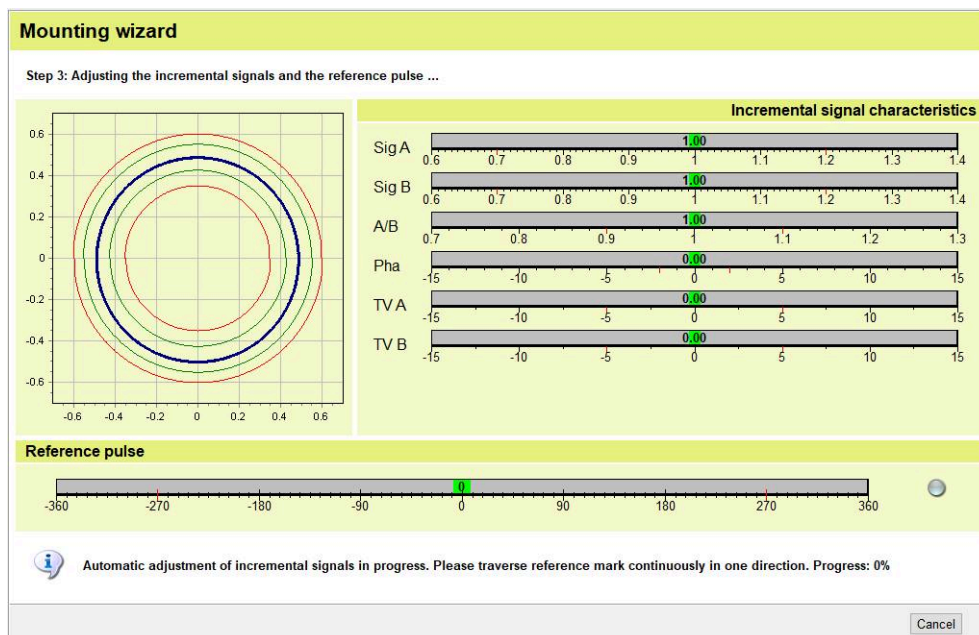


Figure 5: Step 3: Adjusting the incremental signals and the reference pulse message

- ▶ Traverse reference mark until "Progress: 100%" has been reached
- > The **Adjustment was performed successfully** message appears.
- > The adjustment values are saved in the encoder.

- ▶ Click **Next**
- ▶ Click **Exit**
- > The mounting wizard closes.

Repeat this procedure for every scanning head.

3 Installation

This chapter describes the installation of the product. It contains information about the product's connections and instructions about how to correctly connect encoders.

3.1 General information

The connections on the device are protected by dust protection caps from contamination and damage.

NOTICE

Contamination or damage may result if the dust protection caps are missing!

This may impair the proper functioning of the contacts or destroy them.

- ▶ Remove dust protection caps only when connecting measuring devices or peripherals
- ▶ If you remove a measuring device or peripheral, re-attach the dust protection cap to the connection

NOTICE

Incorrect voltage supply range and incorrect wiring!

Danger of product damage and damage to the downstream electronics

- ▶ Do not engage or disengage the connecting cable between the encoder and the downstream electronics while under power

NOTICE

Electrostatic discharge (ESD)!

This product contains electrostatic sensitive components that can be destroyed by electrostatic discharge (ESD).

- ▶ It is essential to observe the safety precautions for handling ESD-sensitive components
- ▶ Never touch connector pins without ensuring proper grounding
- ▶ Wear a grounded ESD wristband when handling product connections



- Observe the minimum distances from sources of interference
- Comply with cable bend radii
- Pay attention to the different encoder connections, depending on the device version

3.2 Definition of the scanning heads

The following section describes how the ERP 1080 *Dplus* is connected to the EIB 74x signal converter. This connection is also applicable to downstream electronics from third-party providers.

The sequence of the scanning heads is prespecified and indicated with an ID label.

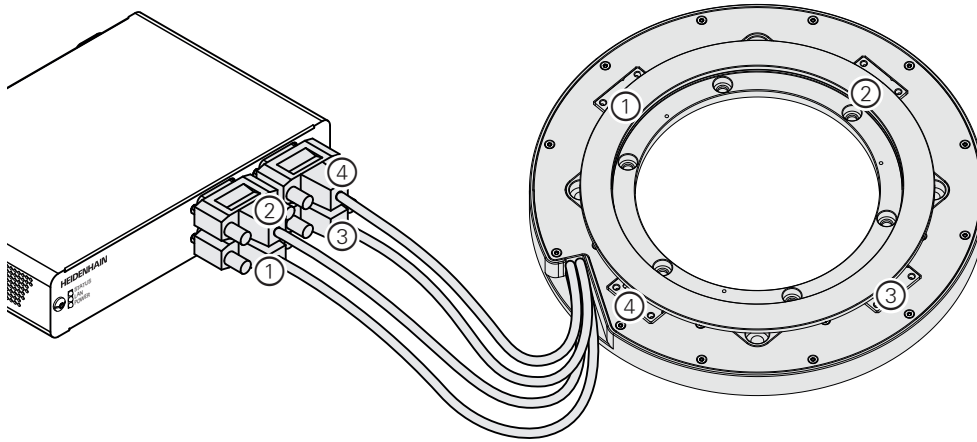


Figure 6: Connection of ERP 1080 *Dplus* to EIB 74x

3.3 Connecting the encoder

To connect the encoder:

- ▶ Ensure sufficient voltage and power supply
- ▶ Remove and save the dust protection cap
- ▶ Connect the encoder connectors tightly to the respective connections
- ▶ If the cable connectors include mounting screws, tighten them only lightly

Pin	Function
1, 3, 7, 9, 11, 14	Incremental signals
2, 4, 10, 12	Power supply
6, 8, 13	Other signals

	4	12	2	10	1	9	3	11	14	7	5/6/8/15	13	/
	Up	Sensor Up	0V	Sensor 0V	A+	A-	B+	B-	R+	R-	/ ¹⁾	/ ¹⁾	/
	BNGN	BU	WHGN	WH	BN	GN	GY	PK	RD	BK	/	VT	YE

1) Pins for homing signals or limit signals, if the encoder supports them

4 Putting into service

This chapter contains all the information necessary for putting the device into operation.

4.1 Overview

To eliminate radial deviations and improve the overall accuracy, the angle encoder includes four scanning heads. In order to attain the desired high accuracy, all scanning head positions must be captured simultaneously and the arithmetic mean value must be calculated.

To be able to average the positions, all positions must be available as absolute position values. Therefore, a reference run must be performed with all scanning heads. Only then can the correct absolute position value be ascertained and output. To establish a clear reference to the defined datum, you have to consider a reference offset.

Procedure

To commission the product, follow the steps below in the given order:

- ▶ **Step 1:** Find reference position
- ▶ **Step 2:** Calculate reference offset
- ▶ **Step 3:** Calculate position value

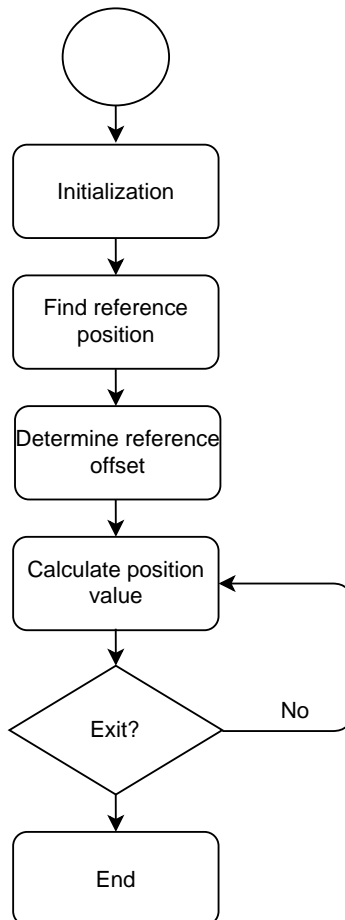


Figure 7: Commissioning flow chart

4.2 Notes

Before you start commissioning, ensure that the test environment is save.
You can put the device into service with an EIB 74x. The commands and an example program are described in the EIB 74x documentation.



For more information, refer to the **EIB 74x** User's Manual.

▶ www.heidenhain.com/documentation

▶ Enter the document ID **752925**

4.3 Finding the reference position

Before the position value formation, you need to reference the incremental encoder.



All scanning heads must be referenced within one revolution. The direction of rotation and the referencing sequence are not relevant for this.

Procedure

Signal period	Number of reference marks
63000	1

4.4 Determining the reference offset

To be able to establish the reference to the absolute datum of the overall system after referencing all scanning heads, you have to define a reference offset. This reference offset will be taken into account during the subsequent position value formation.

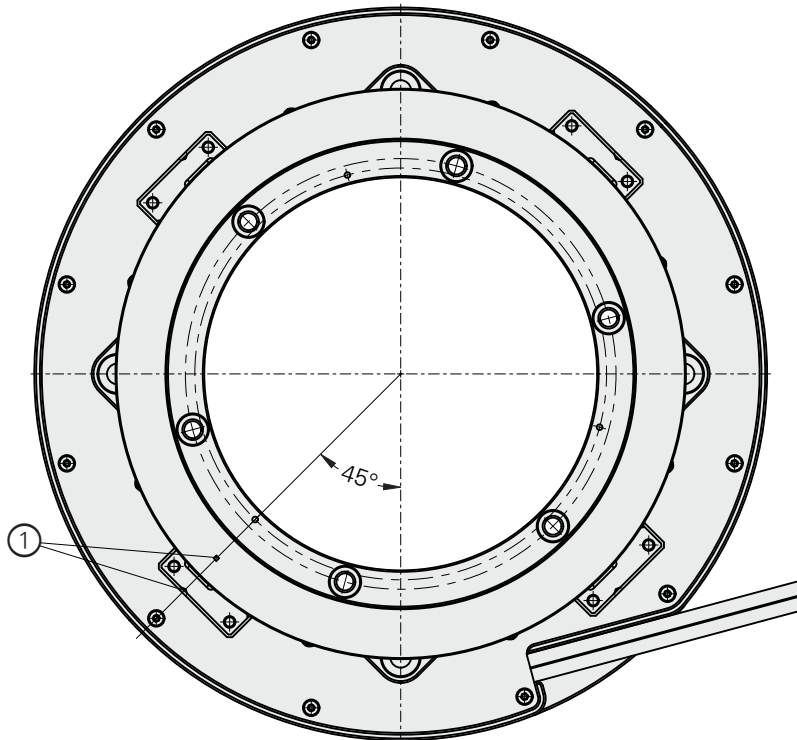


Figure 8: ERP 1080 Dplus in 0° position

1 0° position: RP marking above notch of first scanning head

Procedure

i You must query the positions of the referenced scanning heads simultaneously and calculate the offset according to the following equation.

Calculation

IF ($X1_{abs} > X2_{abs}$) then
 $K_2 = 90^\circ$ else
 $K_2 = 0^\circ$

IF ($X1_{abs} > X3_{abs}$) then
 $K_3 = 90^\circ$ else
 $K_3 = 0^\circ$

IF ($X1_{abs} > X4_{abs}$) then
 $K_4 = 90^\circ$ else
 $K_4 = 0^\circ$

$$Offset = K_2 + K_3 + K_4 - 135^\circ$$

Formula symbols:	Meaning
$K_2 \dots K_4$	Proportional position shift
$X1_{abs} \dots X4_{abs}$	Position of the scanning head
Offset	Offset for the datum according to the Mounting Instructions

4.5 Calculating the position value

For the system to be able to reach the specified accuracy, you need to average the positions of all scanning heads.

i You must query the positions of the referenced scanning heads simultaneously.

i For the reference to the datum of the overall system, you must consider the ascertained offset.

$$X_{avg} = \frac{(X1_{abs} + X2_{abs} + X3_{abs} + X4_{abs})}{4} + Offset$$

Formula symbols:	Meaning
$X1_{abs}$ to $X4_{abs}$	Position of the scanning head
Offset	Offset for the datum according to the Mounting Instructions
X_{avg}	Arithmetic mean value of the inputs $X1_{abs}$ to $X4_{abs}$

Verifying the calculation

You can check the result as follows:

- ▶ Move to the 0° position
- > $X_{avg} = 0^\circ$

Sequence of the position value calculation

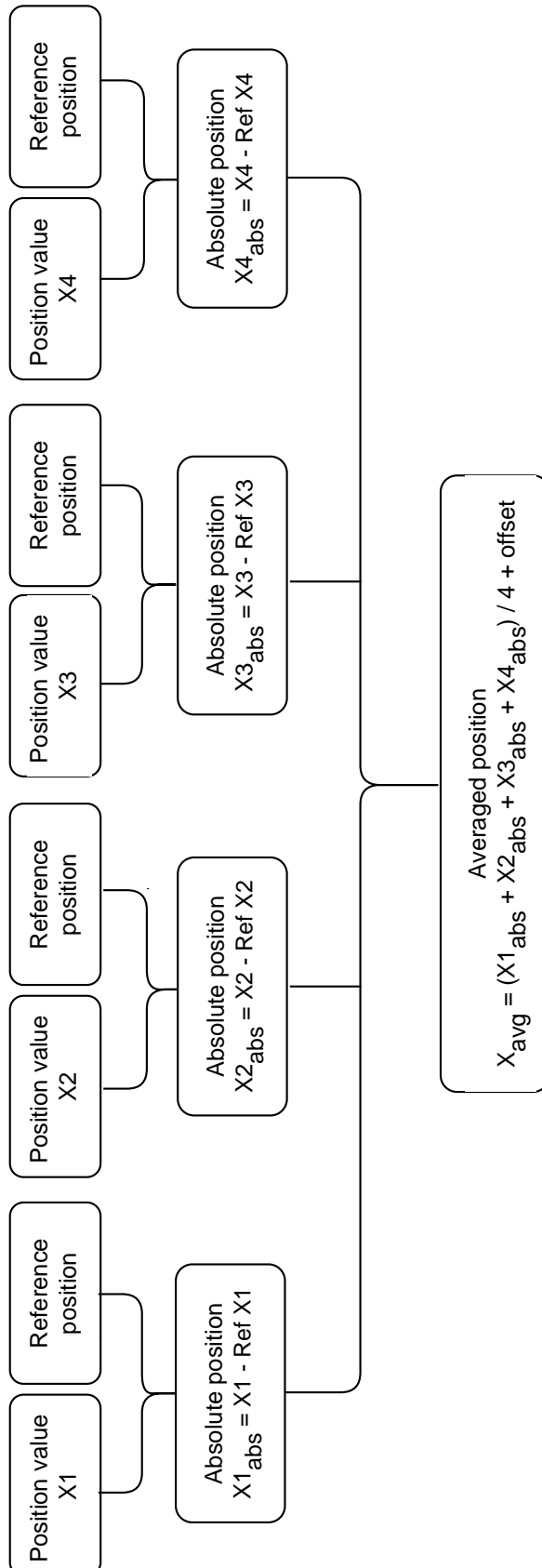


Figure 9: Calculation of position value

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