



KABEA2	A
01	$\phi 4.5$
02	$\phi 6$

- A** = Lagerung Geber Bearing of Rotary encoder
- B** = Befestigungsgewinde
z. B. ISO 4762 - 8.8 MKL 3x M3x10;
Anzugsmoment 1 ± 0.06 Nm Threaded mounting hole
e. g. ISO 4762 - 8.8 MKL 3x M3x10;
Tightening torque 1 ± 0.06 Nm
- M1** = Messpunkt Arbeitstemperatur Measuring point for operating temperature
- M2** = Messpunkt Vibration Measuring point for vibration
- H1** = ROD Referenzmarkenlage
Welle - Flansch $\pm 15^\circ$ ROD reference mark position
shaft - flange $\pm 15^\circ$
- H2** = Gewindetiefe von 5mm auf 7mm
umgestellt im November 2011 Thread depth changed from
5mm to 7mm in November 2011
- H3** = ROD: Drehrichtung der Welle für Aus-
gangssignale gemäß Schnittstel-
lenbeschreibung ROD: Direction of shaft rotation for output
signals as per the interface
description
ROC/ROQ: Drehrichtung der Welle
für steigende Positions-
werte ROC/ROQ: Direction of shaft rotation for
ascending position values

01J	03B	M3 - 7+1 tief/depth (M3 - 5 tief/depth)	H2
WELLA1	FLANA1	a	

Original drawing		Scale		Format		ROD/ROC/ROQ 4xx		ID number:	
1:1		A2		Anschlussmaße / Mating Dimensions		ROD/ROC/ROQ 4xx		Change No. C172391-15	
Dimensions in mm		1:1		A2		Anschlussmaße / Mating Dimensions		Phase: Serie	
								Tolerances as per ISO 8015	
								General Tolerances ISO 2768:1989-mH ± 6 mm: ± 0.2	
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