

HEIDENHAIN



Functional Safety

Product Information

ECN 425 EQN 437

Absolute Rotary Encoders with Hollow Shaft and Expanding Ring Coupling for Safety-Related Applications

ID 1327454-01 ID 1327455-01

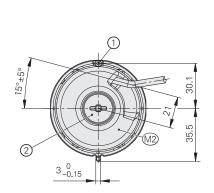
ECN 425, EQN 437

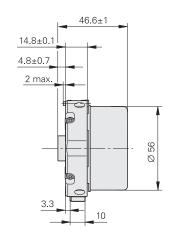
Rotary encoders for absolute position feedback with safe singleturn information

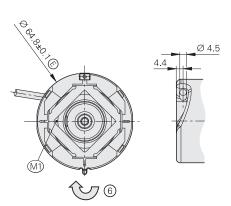
- 65 mm installation diameter
- 07B expanding ring coupling
- 67M blind hollow shaft (Ø 12.7 mm) for axial clamping
- IP64 protection

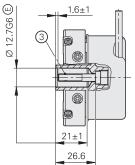


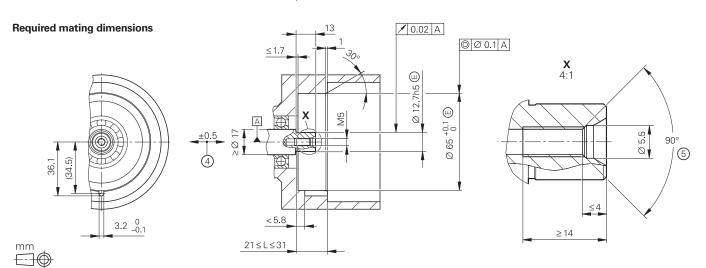












Tolerancing ISO 8015 ISO 2768:1989-mH ≤ 6 mm: ±0.2 mm

- = Bearing of mating shaft
- M1 = Measuring point for operating temperature
- M2 = Measuring point for vibration; see D741714
- 1 = Clamping screw for coupling ring, width A/F 2; tightening torque: 1.25 Nm -0.2 Nm
- 2 = Screw plug, width A/F 3 and 4; tightening torque: 5 Nm +0.5 Nm
- 3 = Screw: DIN 6912 M5x25 08.8 MKL; width A/F 4; tightening torque: 5 Nm +0.5 Nm
- 4 = Compensation of mounting tolerances and thermal expansion; no dynamic motion permitted
- 5 = Chamfer at start of thread is obligatory for material bonding anti-rotation lock
- 6 = Direction of shaft rotation for ascending position values

Specifications	ECN 425 singleturn	EQN 437 multiturn	
Functional safety for applications with up to	As a single-encoder system for monitoring and control-loop functions: • SIL 2 as per EN 61508 (further basis for testing: IEC 61800-5-3) • Category 3, PL d, according to EN ISO 13849-1:2015 Safe in the singleturn range		
PFH ¹⁾	\leq 10 · 10 ⁻⁹ (probability of dangerous failure per hour)		
Safe position ²⁾	Encoder: $\pm 1.76^{\circ}$ (safety-related measuring step: SM = 0.7°) Mechanical coupling: $\pm 2^{\circ}$ (exclusion for loosening of shaft and stator coupling, designed for accelerations of $\leq 300 \text{ m/s}^2$)		
Interface/ordering designation	EnDat 2.2/EnDat22		
Position values per revolution	33554432 (25 bits)		
Revolutions	-	4096 (12 bits)	
Calculation time t _{cal} /clock frequency	≤ 7 µs/≤ 16 MHz		
System accuracy at 20 °C	±20"		
Supply voltage	DC 3.6 V to 14 V		
Power consumption (maximum)	At 3.6 V: ≤ 600 mW At 14 V: ≤ 700 mW	At 3.6 V: ≤ 700 mW At 14 V: ≤ 800 mW	
Current consumption (typical)	At 5 V: 80 mA (without load)	At 5 V: 95 mA (without load)	
Electrical connection	Cable (1 m) with 8-pin M12 coupling (male)		
Cable length ³⁾	≤ 100 m (at clock frequency ≤ 8 MHz) ≤ 20 m (at clock frequency ≤ 16 MHz)		
Shaft	67M blind hollow shaft (Ø 12.7 mm) for axial clamping		
Permissible shaft speed	≤ 12 000 rpm		
Starting torque at 20 °C (typical)	≤ 0.01 Nm		
Moment of inertia of rotor	$\leq 3.6 \cdot 10^{-6} \text{kgm}^2$		
Angular acceleration of rotor	$\leq 5 \cdot 10^4 \text{rad/s}^2$		
Natural frequency f _N (typical)	≥ 1800 Hz		
Permiss. axial motion of measured shaft	≤ ±0.5 mm		
Vibration 55 Hz to 2000 Hz ⁴⁾ Shock 6 ms	$\leq 300 \text{ m/s}^2 \text{ (EN 60068-2-6)}$ $\leq 2000 \text{ m/s}^2 \text{ (EN 60068-2-27)}$		
Operating temperature ⁵⁾	Stationary cable: –30 °C to 100 °C; moving cable: –10 °C to 100 °C		
Trigger threshold for exceeded temperature error message ⁶⁾	125 °C (measuring accuracy of the internal temperature sensor: ±1 K)		
Relative humidity	≤ 93% (40 °C/21 d as per EN 60068-2-78), condensation excluded		
Protection rating EN 60529	IP67 on housing; IP64 at shaft inlet (read about insulation under <i>Electrical safety</i> in the <i>Interfaces of HEIDENHAIN Encoders</i> brochure; contamination from the ingress of fluids must be avoided)		
Mass	≈ 0.3 kg		
ID number	1327454-01	1327455-01	

¹⁾ For use at ≤ 2000 m above sea level

 $^{(\}le 6000 \text{ m} \text{ above sea level upon request})$ 2) Further tolerances may arise in the downstream electronics after position value comparison (contact manufacturer)

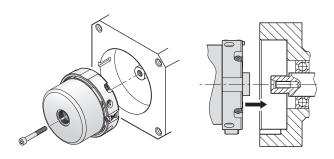
³⁾ See the EnDat description in the *Interfaces of HEIDENHAIN* Encoders brochure)

^{4) 10} Hz to 55 Hz, 4.9 mm constant peak to peak
5) For information on operating temperature, shaft speed, and supply voltage, see *General mechanical information* in the *Rotary Encoders* brochure
6) The internal temperature evaluation is not designed with

functional safety

Mounting

The shaft of the rotary encoder is pressed onto the motor's drive shaft and fastened with a central screw. It is particularly important to ensure that the positivelocking element of the stator coupling securely engages the corresponding slot in the measured shaft. Use a central screw with material-bonding anti-rotation lock (see Mounting accessories). The stator coupling is clamped by means of an axially tightenable screw in a locating hole.





(More information:

For the customer-side mounting design, the material specifications for steel apply to the customer-side shaft. For the customer-side stator, the material specifications for aluminum apply.

Also comply with the other material properties in the Encoders for Servo Drives brochure (ID 208922-xx).

Mounting accessories

Screws

Screws (central screw, mounting screws) are not included in delivery and can be ordered separately.

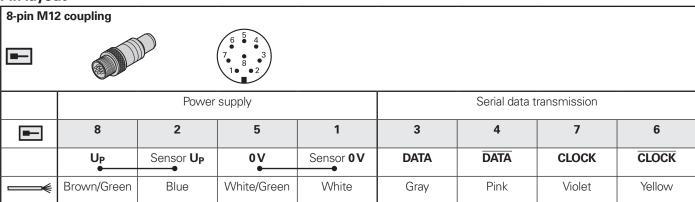
ECN 425, EQN 437 screws ¹⁾			Quantity
Central screw for fastening the shaft	DIN 6912 - M5×25 - 08.8 - MKL	ID 202264-55	10 or 100

¹⁾ With coating for material bonding anti-rotation lock

For more mounting information and mounting aids, see the mounting instructions and the Encoders for Servo Drives brochure. The mounting quality can be inspected with the PWM 21 and ATS software.

Electrical connection

Pin layout



Cable shield connected to housing; UP = Power supply voltage

Sensor: The sense line is connected in the encoder with the corresponding power supply line.

Vacant pins or wires must not be used.

Note for safety-related applications: Only completely assembled HEIDENHAIN cables are qualified. Do not modify cables or exchange their connectors without first consulting with HEIDENHAIN Traunreut.

HEIDENHAIN

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This Product Information document supersedes all previous editions, which thereby become invalid. The basis for ordering from HEIDENHAIN is always the Product Information document edition valid when the order is placed.



(More information:

Comply with the requirements described in the following documents to ensure correct and intended operation:

• Operating Instructions

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