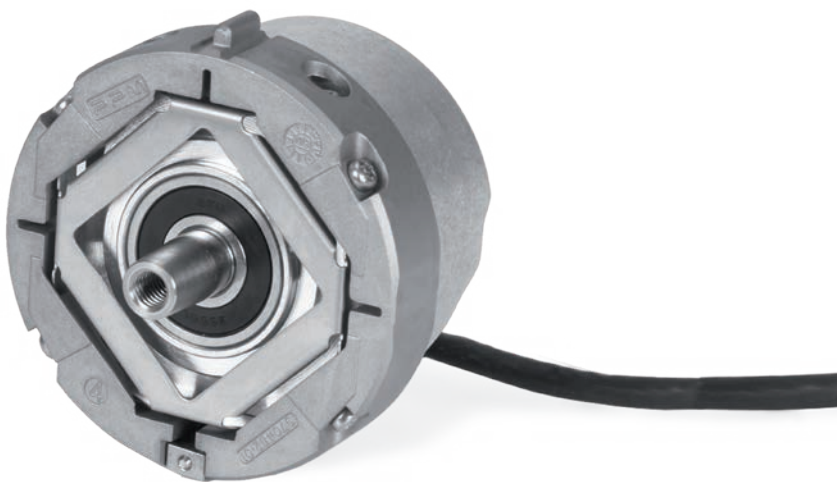




# HEIDENHAIN



**Functional  
Safety**

Product Information

**ECN 425**  
**EQN 437**

Absolute Rotary Encoders  
with Tapered Shaft and  
Expanding Ring Coupling  
for Safety-Related  
Applications

ID 1178028-02

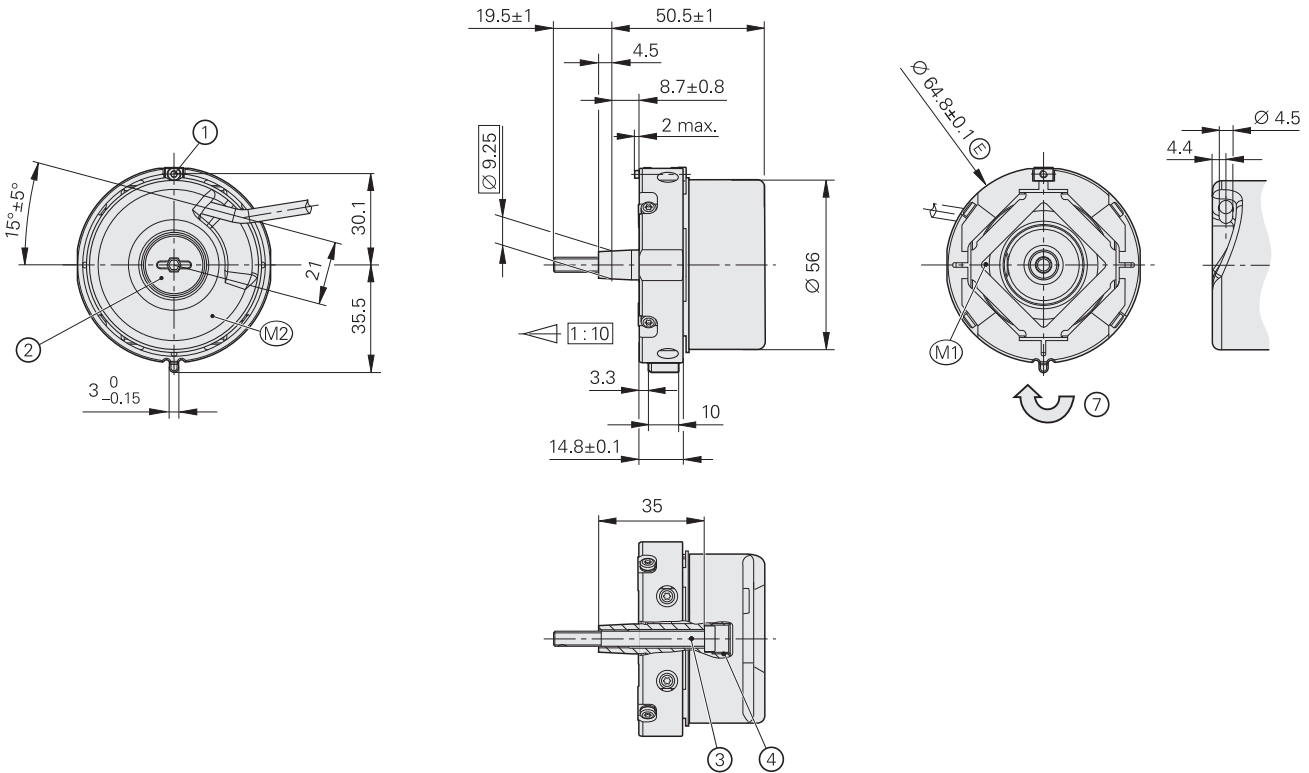
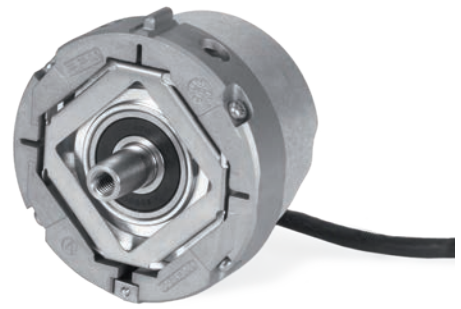
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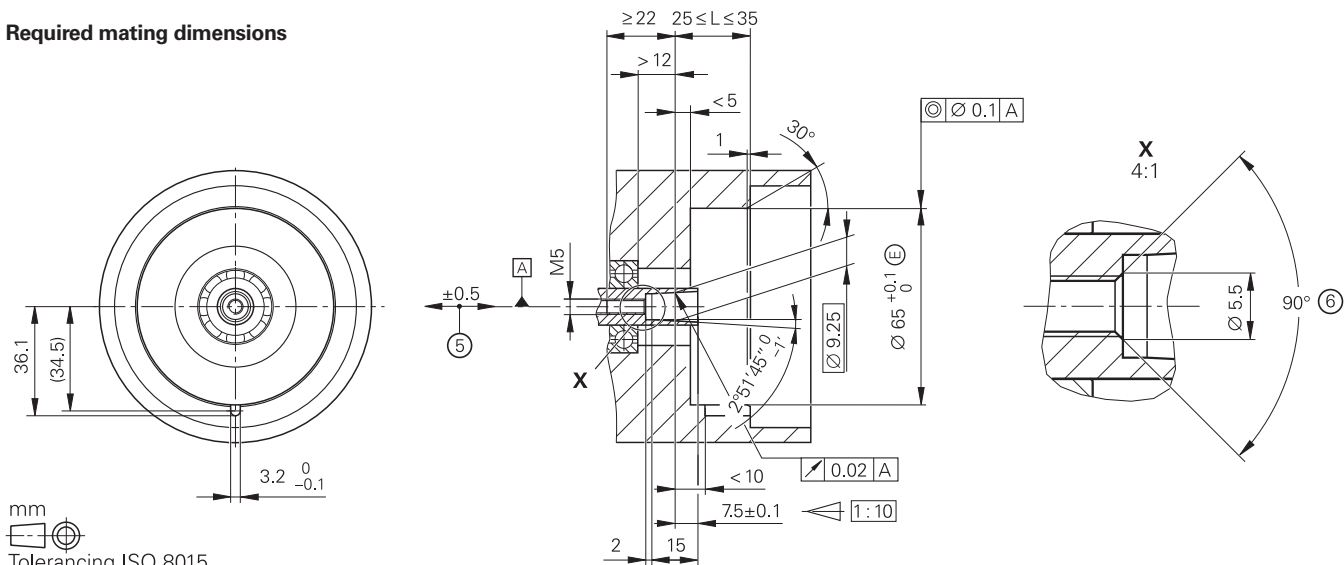
# ECN 425, EQN 437

Rotary encoders for absolute position feedback with safe singleturn information

- 65 mm installation diameter
- 07B expanding ring coupling
- 65B tapered shaft
- IP64 protection



## Required mating dimensions



mm  
 Tolerancing ISO 8015  
 ISO 2768:1989-mH  
 $\leq 6$  mm:  $\pm 0.2$  mm

- ☐ = Bearing of mating shaft
- M1 = Measuring point for operating temperature
- M2 = Measuring point for vibration; see D741714
- 1 = Clamping screw for coupling ring, width A/F 2; tightening torque: 1.25 Nm  $-0.2$  Nm
- 2 = Screw plug, width A/F 3 and 4; tightening torque: 5 Nm  $+0.5$  Nm
- 3 = Screw: DIN 6912 – M5x50 – 08.8 – MKL; width A/F 4; tightening torque: 5 Nm  $+0.5$  Nm
- 4 = M10 back-off thread
- 5 = Compensation of mounting tolerances and thermal expansion; no dynamic motion permitted
- 6 = Chamfer at start of thread is obligatory for material bonding anti-rotation lock
- 7 = Direction of shaft rotation for ascending position values

Specifications	ECN 425 singleturn	EQN 437 multiturn
<b>Functional safety</b> for applications with up to	As a single-encoder system for monitoring and control-loop functions: <ul style="list-style-type: none"> <li>• SIL 2 as per EN 61508 (further basis for testing: IEC 61800-5-3)</li> <li>• Category 3, PL d, according to EN ISO 13849-1:2015</li> </ul> Safe in the singleturn range	
PFH <sup>1)</sup>	≤ 10 · 10 <sup>-9</sup> (probability of dangerous failure per hour)	
Safe position <sup>2)</sup>	Encoder: ±1.76° (safety-related measuring step: SM = 0.7°) Mechanical coupling: ±2° (exclusion for loosening of shaft and stator coupling, designed for accelerations of ≤ 300 m/s <sup>2</sup> )	
Interface/ordering designation	EnDat 2.2/EnDat22	
Position values per revolution	33554432 (25 bits)	
Revolutions	–	4096 (12 bits)
Calculation time t <sub>cal</sub> /clock frequency	≤ 7 μs/≤ 16 MHz	
<b>System accuracy</b> at 20 °C	±20"	
Supply voltage	DC 3.6 V to 14 V	
Power consumption (maximum)	At 3.6 V: ≤ 600 mW At 14 V: ≤ 700 mW	At 3.6 V: ≤ 700 mW At 14 V: ≤ 800 mW
Current consumption (typical)	At 5 V: 80 mA (without load)	At 5 V: 95 mA (without load)
<b>Electrical connection</b>	Cable (1 m) with 8-pin M12 coupling (male)	
Cable length <sup>3)</sup>	≤ 100 m (at clock frequency ≤ 8 MHz) ≤ 20 m (at clock frequency ≤ 16 MHz)	
Shaft	65B tapered shaft (Ø 9.25 mm); taper 1:10	
Permissible shaft speed	≤ 15000 rpm	≤ 12000 rpm
Starting torque at 20 °C (typical)	≤ 0.01 Nm	
Moment of inertia of rotor	≤ 2.6 · 10 <sup>-6</sup> kgm <sup>2</sup>	
Angular acceleration of rotor	≤ 1 · 10 <sup>5</sup> rad/s <sup>2</sup>	
Natural frequency f <sub>N</sub> (typical)	≥ 1800 Hz	
Permiss. axial motion of measured shaft	≤ ±0.5 mm	
<b>Vibration</b> 55 Hz to 2000 Hz <sup>4)</sup> <b>Shock</b> 6 ms	≤ 300 m/s <sup>2</sup> (EN 60068-2-6) ≤ 2000 m/s <sup>2</sup> (EN 60068-2-27)	
<b>Operating temperature</b> <sup>5)</sup>	Stationary cable: -40 °C to 100 °C; Moving cable: -10 °C to 100 °C	
<b>Trigger threshold</b> for exceeded temperature error message <sup>6)</sup>	125 °C (measuring accuracy of the internal temperature sensor: ±1 K)	
<b>Relative humidity</b>	≤ 93% (40 °C/21 d as per EN 60068-2-78), condensation excluded	
<b>Protection rating</b> EN 60529	IP67 on housing; IP64 at shaft inlet (read about insulation under <i>Electrical safety</i> in the <i>Interfaces of HEIDENHAIN Encoders</i> brochure; contamination from the ingress of fluids must be avoided)	
<b>Mass</b>	≈ 0.3 kg	
<b>ID number</b>	1178028-02	1178029-02

<sup>1)</sup> For use at ≤ 2000 m above sea level  
(≤ 6000 m above sea level upon request)

<sup>2)</sup> Further tolerances may arise in the downstream electronics after position value comparison (contact manufacturer)

<sup>3)</sup> See the EnDat description in the *Interfaces of HEIDENHAIN Encoders* brochure)

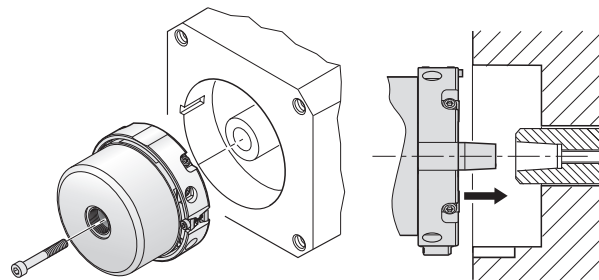
<sup>4)</sup> 10 Hz to 55 Hz, 4.9 mm constant peak to peak

<sup>5)</sup> For information on operating temperature, shaft speed, and supply voltage, see *General mechanical information* in the *Rotary Encoders* brochure

<sup>6)</sup> The internal temperature evaluation is not designed with functional safety

# Mounting

The tapered shaft of the rotary encoder is pressed onto the measured shaft and fastened with a central screw. It is particularly important to ensure that the positive-locking element of the stator coupling securely engages the corresponding slot in the measured shaft. Use a central screw with material-bonding anti-rotation lock (see *Mounting accessories*). The stator coupling is clamped by means of an axially tightenable screw in a locating hole.



## More information:

For the customer-side mounting design, the material specifications for steel apply to the customer-side shaft. For the customer-side stator, the material specifications for aluminum apply.

Also comply with the other material properties in the *Encoders for Servo Drives* brochure (ID 208922-xx).

## Mounting accessories

### Screws

Screws (central screw, mounting screws) are not included in delivery and can be ordered separately.


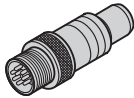



ECN 425, EQN 437 screws <sup>1)</sup>			Quantity
<b>Central screw</b> for fastening the shaft	DIN 6912 – M5×50 – 08.8 – MKL	ID 202264-54	10 or 100

<sup>1)</sup> With coating for material bonding anti-rotation lock

**For more mounting information and mounting aids, see the mounting instructions and the *Encoders for Servo Drives* brochure. The mounting quality can be inspected with the PWM 21 and ATS software.**

# Electrical connection

## Pin layout

8-pin M12 coupling								
								
	Power supply				Serial data transmission			
	<b>8</b>	<b>2</b>	<b>5</b>	<b>1</b>	<b>3</b>	<b>4</b>	<b>7</b>	<b>6</b>
	$U_P$	Sensor $U_P$	$0V$	Sensor $0V$	<b>DATA</b>	$\overline{\text{DATA}}$	<b>CLOCK</b>	$\overline{\text{CLOCK}}$
	Brown/Green	Blue	White/Green	White	Gray	Pink	Violet	Yellow

**Cable shield** connected to housing;  $U_P$  = Power supply voltage

**Sensor:** The sense line is connected in the encoder with the corresponding power supply line.

Vacant pins or wires must not be used!

**Note for safety-related applications:** Only completely assembled HEIDENHAIN cables are qualified. Do not modify cables or exchange their connectors without first consulting with HEIDENHAIN Traunreut!

## HEIDENHAIN

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### More information:

Comply with the requirements described in the following documents to ensure correct and intended operation:

- Operating Instructions

1379276-xx